

Theory of Finsler spaces with (λ, β) – Metric

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ABSTRACT

The aim of this paper is to introduce and study the concept of (λ, β) – metric and a number of propositions and theorems have been worked out for a (λ, β) – metric, where $\lambda^m = a_{i_1, i_2, \dots, i_m} y^{i_1} y^{i_2} \dots y^{i_m}$ is a m^{th} -root metric and $\beta = b_i(x) y^i$ is a one form metric.

Keywords: Finsler space with (λ, β) – metric, m^{th} -root metric, one form metric, curvature tensor, torsion tensor.

INTRODUCTION

We begin with recalling some notations and basic definitions that are used in this paper.

Definition 1: Finsler space

Suppose that we are given a function $L(x^i, y^j)$ of the line element (x^i, y^j) of a curve defined in R . We shall assume L as a function of class at least C^5 in all its $2n$ -arguments. If we define the infinitesimal distance ds between two points $P(x^i)$ and $Q(x^i + dx^i)$ of R by the relation $ds = L(x^i, dx^i)$ then, the manifold M^n equipped with the fundamental function L defining the metric is called a Finsler space if $L(x^i + dx^i)$ satisfies the following condition:-

A -The function $L(x^i, y^j)$ is positively homogeneous of degree one in y^i i. e.,

$$L(x^i, ky^j) = k L(x^i, y^j), \quad k > 0$$

That is, the arc length of curve is independent of the choice of parameter t .

B -The function $L(x^i, y^j)$ is positive if not all y^i vanish simultaneously, i.e.,

$$L(x^i, y^j) > 0 \quad \text{with} \quad \sum_i (y^i)^2 \neq 0$$

That is, the distance between two distinct points is positive.

C- The quartic form,

$$\partial_i \partial_j L^2(x^i, y^j) \xi^i \xi^j = \frac{\partial^2 L^2(x^i, y^j)}{\partial y^i \partial y^j} \xi^i \xi^j \text{ is assumed to}$$

be positive definite for all any variable ξ^i .

That is, $L(x^i, y^j)$ is a convex function in y^i (Matsumoto, 1986)

Definition 2: Finsler connection

A Finsler connection $F\Gamma$ is defined as tried

$(F_{jk}^i(x, y), N_j^i(x, y), V_{jk}^i(x, y))$ as follows:

(i) $F_{jk}^i(x, y)$ are called the connection coefficients of h-connection which obey the usual transformation law of connection coefficients of a connection

$$\bar{F}_{bc}^a(\bar{x}, \bar{y}) = F_{jk}^i(x, y) \bar{X}_i^a \bar{X}_b^j \bar{X}_c^k + \bar{X}_i^a \partial_c \bar{X}_b^i$$

(‘h’ is the abbreviation of ‘horizontal’.)

(ii) $N_j^i(x, y)$ are called the connection coefficients of non-linear connection which obey the transformation law

$$\bar{N}_b^a(\bar{x}, \bar{y}) = N_j^i(x, y) \bar{X}_i^a \bar{X}_b^j + \bar{X}_i^a \partial_b \bar{X}_c^i \bar{y}^c$$

(iii) $V_{jk}^i(x, y)$ are called the connection coefficients of v-connection which are components of a tensor field of (1,2)-type. (‘v’ is the abbreviation of ‘vertical’.) (Antonelli *et al.* 1993).

Definition 3: h and v- covariant derivative,

A tensor field $T_j^i(x, y)$, for instance, of (1,1)-type we have first the h-covariant derivative ${}^h T$ whose components are given by

$$T_{jk}^i = \delta_k T_j^i + T_j^r F_{rk}^i - T_r^i F_{jk}^r \dots \dots \dots (1)$$

where, δ_k is a differential operator $\delta_k = \partial_k - N_k^r \partial_r$.

Secondly, we have the v-covariant derivative ${}^v T$ whose components are given by

$$T_j^i |_{|k} = \partial_k T_j^i + T_j^r V_{rk}^i - T_r^i V_{jk}^r \dots \dots \dots (2)$$

(Matsumoto, 1986)

Definition 4: Berwald connection

The Berwald connection $B\Gamma = (G_{jk}^i, G_j^i, 0)$ is uniquely determined from function $L(x, y)$ of F^n by the following five axioms:-

$$L_{|i} = 0, \text{ i.e. } L\text{-metrical} \dots\dots\dots(B1)$$

$$(h) \text{ h-torsion: } T_{jk}^i = 0 \dots\dots\dots(B2)$$

$$\text{deflection: } D_j^i = 0 \dots\dots\dots(B3)$$

$$(v) \text{ hv-torsion: } P_{jk}^i = 0 \dots\dots\dots(B4)$$

$$(h) \text{ hv-torsion: } C_{jk}^i = 0 \dots\dots\dots(B5)$$

(Matsumoto, 1992).

Definition 5: The Cartan connection $C\Gamma = (\Gamma_{jk}^{*i}, G_j^i, C_{jk}^i)$

is uniquely determined from function $L(x, y)$ of F^n by the following five axioms:-

$$g_{ijk} = 0 \text{ i.e. h-metrical} \dots\dots\dots(C1)$$

$$(h) \text{ h-torsion: } T_{jk}^i = 0 \dots\dots\dots(C2)$$

$$\text{deflection tensor field } D_j^i = 0 \dots\dots\dots(C3)$$

$$g_{ij} |_{|k} = 0, \text{ i.e. v-metrical} \dots\dots\dots(C4)$$

$$(h) \text{ h-torsion: } S_{jk}^i = 0. \dots\dots\dots(C5)$$

(Matsumoto, M. 1992).

Matsumoto (1995) introduce the concept of m^{th} -root metric on a differentiable manifold with the local coordinate x^i , is defined by

$$L(x, y) = \{a_{i_1 i_2 \dots i_m}(x) y^{i_1} y^{i_2} y^{i_3} \dots y^{i_m}\}^{1/3} \dots\dots\dots(3)$$

where, $a_{i_1 i_2 \dots i_m}(x)$ are components of a symmetric tensor field of $(0, m)$ -type depending on the position x alone, and a Finsler space with a m^{th} -root metric is called the m^{th} -root Finsler space (Shimada, 1979; Kropina 1961; Wagner, 1938; Wagner, 1943). They studying the m^{th} -root Finsler spaces with a cubic metric as a generalization of Euclidean or Riemannian geometry. In 1941, Randers co-relate the Finsler Theory with the unified field theory of gravitation and electromagnetism. The formula for the length ds of a line-element dx^i must necessarily be homogeneous of first degree in dx^i . The simplest “eccentric” line-element possessing this property, and of course being invariant, is

$$ds = \{a_{ij}(x) dx^i dx^j\}^{1/2} + b_i(x) dx^i \dots\dots\dots(4)$$

Where $a_{ij}(x)$ is the fundamental tensor of the Riemannian affine connection, and b_i is a covariant vector determining the displacement of the centre of the indicatrix.”

In the present paper, we shall study Finsler space with the fundamental function $L(\lambda, \beta)$. We have workout some basic tensors namely h_{ij}, g_{ij}, C_{ijk} and g^{ij} and also workout certain propositions regarding the Finsler space with (λ, β) -metric.

Basic tensors of (λ, β) -metric

Definition 6: A Finsler metric $L(x, y)$ is called a (λ, β) -metric, when L is positively homogeneous function $L(\lambda, \beta)$ of first degree in two variables, λ and β , where $\lambda^m = a_{i_1 i_2 \dots i_m}(x) y^{i_1} y^{i_2} y^{i_3} \dots y^{i_m}$ is m^{th} root metric and $\beta = b_i(x) y^i$ is a one-form metric (Matsumoto & Shimada, 1978).

Throughout, the present paper, following notations are adopted

$$a_k = a_{i_1 i_2 \dots i_{m-1}}(x) y^{i_1} y^{i_2} y^{i_3} \dots y^{i_{m-1}}$$

$$a_{ij} = (m-1) a_{i_1 i_2 \dots i_{m-2}}(x) y^{i_1} y^{i_2} \dots y^{i_{m-2}}$$

$$a^{ij} b_j = B^i \text{ and } a^{ij} a_j = a^i$$

where, (a^{ij}) is the inverse matrix of (a_{ij}) . Further, subscripts λ, β denote partial differentiations with respect to λ, β respectively. As for a (λ, β) -metric, $L = L(\lambda, \beta) \dots\dots\dots(5)$

Differentiating (5), with respect to y^i , we get

$$l_i = \dot{\partial}_i L = \frac{L_{\lambda}}{\lambda^{m-1}} a_i + L_{\beta} b_i \dots\dots\dots(6)$$

Equation (6) can also be written as

$$y_i = L l_i = L(\dot{\partial}_i L) = \frac{LL_{\lambda}}{\lambda^{m-1}} a_i + LL_{\beta} b_i \dots\dots\dots(7)$$

Again differentiating (6), with respect to, y^j , we have the angular metric tensor $h_{ij} = L(\dot{\partial}_i \dot{\partial}_j L)$, as

$$h_{ij} = p_{-(m-2)} a_{ij} + q_0 b_i b_j + q_{-(m-1)} (a_i b_j + a_j b_i) + q_{-(2m-2)} a_i a_j \dots\dots\dots(8)$$

where, $p_{-(m-2)} = \frac{LL_{\lambda}}{\lambda^{m-1}}, q_0 = LL_{\beta\beta}, q_{-(m-1)} = \frac{LL_{\lambda\beta}}{\lambda^{m-1}}$,

$$q_{-(2m-2)} = \frac{L}{\lambda^{2m-2}} \left(L_{\lambda\lambda} - \frac{(m-1)L_{\lambda}}{\lambda} \right) \dots\dots\dots(8)'$$

Owing to the homogeneity or $h_{ij}y^j = 0$, we have two identities,

$$\begin{cases} p_{-(m-2)} + q_{-(m-1)}\beta + q_{-(2m-2)}\lambda^m = 0 \\ q_0\beta + q_{-(m-1)}\lambda^m = 0 \end{cases} \dots\dots\dots(9)$$

Since a_i and b_i are two independent vector fields, hence, we must have.

Again,

$$\begin{aligned} g_{ij} &= h_{ij} + l_i l_j \dots\dots\dots(10) \\ g_{ij} &= p_{-(m-2)}a_{ij} + p_0b_i b_j + p_{-(m-1)}(a_i b_j + a_j b_i) + p_{-(2m-2)}a_i a_j \end{aligned}$$

where, $p_0 = q_0 + L_{\beta}^2$, $p_{-(m-1)} = q_{-(m-1)} + \frac{L_{\lambda}L_{\beta}}{\lambda^{m-1}}$,

$$p_{-(2m-2)} = q_{-(2m-2)} + \frac{L_{\lambda}^2}{\lambda^{2m-2}} \dots\dots\dots(10)'$$

Using (9) and (10)', we get

$$\begin{cases} p_0\beta + p_{-(m-1)}\lambda^m = LL_{\beta} \\ p_{-(m-1)}\beta + p_{-(2m-2)}\lambda^m = 0 \end{cases} \dots\dots\dots(11)$$

It is well known that

Proposition 1: Let a non-singular symmetric n-matrix (A_{ij}) and n quantities c_i be given, and put

$B_{ij} = A_{ij} + c_i c_j$. The inverse matrix (B^{ij}) of (B_{ij}) and the $\det(B_{ij})$ are given by,

$$B^{ij} = A^{ij} - \frac{1}{(1+c^2)}c^i c^j, \quad \det(B_{ij}) = A(1+c^2)$$

where, (A^{ij}) is the inverse matrix of (A_{ij}) , $A = \det(A_{ij})$, $c^i = A^{ij}c_j$, and $c^2 = c^i c_i$ (Matsumoto, 1992).

From (10), the components g_{ij} may be written as,

$$g_{ij} = p_{-(m-1)}a_{ij} + c_i c_j + d_i d_j$$

where, we put,

$$c_i = \pi b_i, \quad d_i = \pi_0 b_i + \pi_{-(m-1)}a_i$$

$$\pi^2 + \pi_0^2 = p_0 \cdot \pi_0 \pi_{-(m-1)} = p_{-(m-1)},$$

$$\pi_{-(m-1)}^2 = p_{-(2m-2)}$$

we get $B_{ij} = p_{-(m-2)}a_{ij} + c_i c_j$, then we have, $g_{ij} = B_{ij} + d_i d_j$.

From, definition of B^{ij} , we have $B_{ij}B^{ik} = \delta_i^k$.

Then,

$$B^{ij} = \frac{1}{p_{-(m-2)}} \left(a^{ij} - \frac{c^i c^j}{p_{-(m-2)} + c^2} \right)$$

where, a^{ij} is reciprocal of a_{ij} , $c^i = a^{ij}c_j$, and

$c^2 = c^i c_i$. Now, by using Proposition 1, we have

$$g^{ij} = B^{ij} - \frac{d^i d^j}{1+d^2}$$

where, $d^i = B^{ij}d_j$, $d^i d_i = d^2$

$$|g_{ij}| = |B_{ij}|(1+d^2) = p_{-(m-2)}a_{ij} \left| \frac{(p_{-(m-2)} + c^2)}{p_{-(m-2)}}(1+d^2) \right|$$

$$|g_{ij}| = p_{-(m-2)}^{n-1} a (p_{-(m-2)} + c^2)(1+d^2)$$

where a is the determinant of a_{ij} .

$$g^{ij} = \frac{1}{p_{-(m-2)}} a^{ij} - \frac{c^i c^j}{p_{-(m-2)}(p_{-(m-2)} + c^2)} - \frac{d^i d^j}{1+d^2}$$

Now,

$$d^i = B^{ij}d_j = \frac{1}{p_{-(m-2)}} \left[\frac{(\pi_0 p_{-(m-2)} - \pi^2 \pi_{-(m-1)} \bar{a})}{(p_{-(m-2)} + c^2)} B^i + \pi_{-(m-1)} a^i \right]$$

where, $B^i b_i = b^2 = a^{im} b_m b_i$,

$$a_i B^i = a^{im} a_i b_m = a^i b_i = \bar{a}, \quad \pi^2 b^2 = c^2$$

$$\text{Again, } d^i d^j = -\frac{1}{p_{-(m-2)}^2} \left[\frac{(\pi_0 p_{-(m-2)} - \pi^2 \pi_{-(m-1)} \bar{a})^2}{(p_{-(m-2)} + c^2)^2} B^i B^j \right]$$

$$+ \frac{(\pi_0 p_{-(m-2)} - \pi^2 \pi_{-(m-1)} \bar{a})}{(p_{-(m-2)} + c^2)} \pi_{-(m-1)} (B^i a^j + B^j a^i) + \pi_{-(m-1)}^2 a^i a^j$$

$$\text{Or } d^i d^j = \frac{1}{p_{-(m-2)}^2} \left[\frac{(\pi_0 p_{-(m-2)} - \pi^2 \pi_{-(m-1)} \bar{a})^2}{(p_{-(m-2)} + c^2)^2} B^i B^j \right]$$

$$+ \frac{(p_{-(m-1)} p_{-(m-2)} - \pi^2 p_{-(2m-2)} \bar{a})}{(p_{-(m-2)} + c^2)} (B^i a^j + B^j a^i) + p_{-(2m-2)} a^i a^j$$

Now,

$$d^2 = d_i d^i = \frac{1}{p_{-(m-2)}(p_{-(m-2)} + c^2)} [\pi_0^2 b^2 p_{-(m-2)} + 2p_{-(m-1)} p_{-(m-2)} \bar{a} - p_{-(m-1)}^2 \bar{a}^2 + p_{-(m-2)} p_{-(2m-2)} a^2 + p_{-(2m-2)} c^2 a^2].$$

Again,

$$|g_{ij}| = p_{-(m-2)}^{n-1} a(p_{-(m-2)} + c^2)(1 + d^2) = p_{-(m-2)}^{n-1} a \tau$$

where,

$$\tau = p_{-(m-2)} \{p_{-(m-2)} + \pi_0^2 b^2 + p_{-(m-2)} \bar{a}\} + \{p_{-(m-1)} p_{-(m-2)} \bar{a} - p_{-(m-1)}^2 \bar{a}^2\} + \{p_{-(m-2)} p_{-(2m-2)} a^2 + p_{-(2m-2)} a^2 c^2\}.$$

Thus, the reciprocal of (g_{ij}) is given by

$$g^{ij} = \frac{1}{p_{-(m-2)}} a^{ij} - SB^i B^j - S(B^i a^j + B^j a^i) - Sa^i a^j \dots\dots\dots(12)$$

where,

$$S_{2m-4} = \frac{\pi_0^2 p_{-(m-2)}^2 + \pi^2 (\tau + \pi^2 p_{-(2m-2)} \bar{a}^2 - 2p_{-(m-1)} p_{-(m-2)} \bar{a})}{\tau p_{-(m-2)} \{p_{-(m-2)} + c^2\}}$$

$$S_{m-3} = \frac{p_{-(m-1)} p_{-(m-2)} - \pi^2 p_{-(2m-2)} \bar{a}}{\tau p_{-(m-2)}}$$

$$S_{-(2m-4)} = \frac{p_{-(m-2)} p_{-(2m-2)} + c^2 p_{-(2m-2)}}{\tau p_{-(m-2)}} \dots\dots\dots(12)'$$

Differentiating (12) by y^k , we get,

$$2C_{ijk} = 2p_{-(m-2)} a_{ijk} + p_{0\beta} b_i b_j b_k + \Pi \{P_i a_{jk} + p_{-(m-1)\beta} a_i b_j b_k + \frac{p_{-(m-1)\lambda}}{\lambda^{m-1}} a_i a_j b_k\} + \frac{p_{-(2m-2)}}{\lambda^{m-1}} a_i a_j a_k \dots\dots\dots(13)$$

where, Π denotes the sum of cyclic permutation of $i, j,$

$k.$

$$P_i = p_{-(2m-2)} a_i + p_{-(m-1)} b_i$$

$$2p_{-(m-2)} c_{ijk} = 2p_{-(m-2)}^2 a_{ijk} + r_{-(m-1)} b_i b_j b_k$$

$$\text{or, } + \prod_{(ijk)} \{P_i h_{jk} + r_{-(2m-2)} a_i b_j b_k$$

$$+ r_{-(3m-3)} a_i a_j b_k\} + r_{-(4m-4)} a_i a_j a_k \dots\dots\dots(13)$$

where,

$$r_{-(m-1)} = p_{0\beta} p_{-(m-2)} - 3q_0 p_{-(m-1)}, \dots\dots\dots(13a)'$$

$$r_{-(2m-2)} = p_{-(m-1)\beta} p_{-(m-2)} - q_0 p_{-(2m-2)} - 2p_{-(m-1)} q_{-(m-1)}$$

$$r_{-(3m-3)} = \frac{p_{-(m-1)\lambda} p_{-(m-2)}}{\lambda^{m-1}} - q_{-(2m-2)} p_{-(m-1)} - 2p_{-(2m-2)} q_{-(m-1)},$$

$$r_{-(4m-4)} = \frac{p_{-(m-2)} p_{-(2m-2)\lambda}}{\lambda^{m-1}} - 3q_{-(2m-2)} p_{-(2m-2)}$$

Proposition 2: The normalized supporting element l_i , angular metric tensor h_{ij} , metric tensor g_{ij} and (h) hv-torsion tensor C_{ijk} of Finsler space with (λ, β) -metric are given by (6), (8), (10) and (13a) respectively.

Proposition 3: The reciprocal of the metric tensor g_{ij} of (λ, β) -metric is given by (12).

Proposition 4: The coefficients

$$r_{-(m-1)}, r_{-(2m-2)}, r_{-(3m-3)}, r_{-(4m-4)}$$
 defined in (13a)' satisfy the following relation

$$r_{-n(m-1)} \beta + r_{-(n+1)(m-1)} \lambda^m = 0, \dots\dots\dots(14)$$

where $n = 1, 2, 3.$

Now, from (11) and (14), we have

$$p_{-(2m-2)} = \phi p_{-(m-1)},$$

$$r_{-(n+1)(m-1)} = \phi^n r_{-(m-1)}, n = 1, 2, 3 \dots\dots\dots(15)$$

$$\text{where, } \phi = -\frac{\beta}{\lambda^m}.$$

Using relation (15) in (13a), we easily get

$$2p_{-(m-2)} C_{ijk} = 2p_{-(m-2)}^2 a_{ijk} + \Pi (H_{jk} P_i) \dots\dots\dots(13b)$$

$$\text{where, } H_{ij} = h_{ij} + \frac{r_{-(m-1)}}{3p_{-(m-1)}^3} P_i P_j.$$

Further, by direct computation from C_{ijk} and g^{ij} , we have,

$$C_i = p_{-(m-2)} a_{ijk} g^{jk} + Aa_i + Bb_i \dots\dots\dots(16)$$

where A and B are certain scalar.

If the Finsler space (F^n) is C -reducible, then

$$C_{ijk} = \frac{1}{(n+1)} \Pi (h_{ij} C_k) \dots\dots\dots(17)$$

from (13b) and (17), it follows that,

$$a_{ijk} + \frac{r_{-(m-1)}}{2p_{-(m-1)}^3 p_{-(m-2)}^2} P_i P_j P_k = \Pi_{(ijk)} h_{ij} N_k \dots\dots\dots(18)$$

where, $N_k = \frac{2p_{-(m-2)}}{n+1} C_k - P_k$. Conversely, If (18), is satisfied for certain covariant vector N_k , then from 3b) we have

$$2p_{-(m-2)} C_{ijk} = \Pi_{(ijk)} (h_{ij} (P_k + N_k)) \dots\dots(19)$$

which gives (17). Thus, we have,

Theorem 1: A Finsler space with (λ, β) -metric is C-reducible iff equation (18) holds.

Important tensors of (λ, β) -metric

It follow from (13b) and (12), that the components C_{jk}^i of the (h)hv-torsion tensor $C\Gamma$ are given by,

$$2p_{-(m-2)} C_{jk}^i = 2p_{-(m-2)}^2 a_{jk}^i + (\delta_j^i P_k - l_j^i P_k) + (\delta_k^i P_j - l_k^i P_j) + \frac{r_{-(m-1)}}{p_{-(m-1)}^3} P^i P_j P_k + h_{jk} P^i \dots\dots\dots(20)$$

where, $P_i g^{ik} = P^j$, $g^{ij} l_j = l^i$, $a_{ijk} g^{ri} = a_{ijk}^r$.

Again from (13b) and (20), we have,

$$4p_{-(m-2)}^2 C_{hk}^r C_{rij} = 4p_{-(m-2)}^4 a_{hk}^r a_{rij} + 2p_{-(m-2)}^2 \Pi_{(ijk)} (a_{ijk} P_h) - \frac{r_{-(m-1)} \bar{P}}{p_{-(m-1)}^3 L^2} \Pi_{(ijkh)} (P_i P_j P_k l_h) - \frac{2p_{-(m-2)}^2}{L} [a_{ij} (l_h P_k + l_k P_h)] + \frac{2p_{-(m-2)}^2 r_{-(m-1)}}{p_{-(m-1)}^3} a_{rij} p^r p_h p_k + \frac{2p_{-(m-2)}^2 r_{-(m-1)}}{p_{-(m-1)}^3} a_{hk}^r p_r p_i p_j + p_{-(m-2)}^2 a_{rij} p^r h_{hk} + 2 p_{-(m-2)}^2 a_{hk}^r p_r h_{ij} - p_{-(m-2)}^2 [a_{hk}^r l_r (l_i P_j + l_j P_i)] + [h_{ih} p_j p_k + h_{ik} p_h p_j + h_{ij} P_k P_i + h_{jk} P_i P_h + 2h_{ij} P_k P_h + 2h_{hk} P_i P_j] + \frac{r_{-(m-1)} P^2}{p_{-(m-1)}^3 L^4} [h_{ij} + \frac{r_{-(m-1)}}{p_{-(m-1)}^3} P_i P_j] P_k P_h - \frac{\bar{P}}{L^2} h_{ij} (l_h P_k + l_k P_h) - \frac{\bar{P}}{L^2} h_{hk} (l_i P_j + l_j P_i) + \frac{r_{-(m-1)} P^2}{p_{-(m-1)}^3} h_{hk} P_i P_j + \frac{4r_{-(m-1)}}{p_{-(m-1)}^3} P_i P_j P_k P_h. \dots\dots\dots(21)$$

where, $a_{irk} l^r = \frac{a_{ik}}{L}$, $P^r l_r = \frac{\bar{P}}{L^2}$, $P^r P_r = \frac{P^2}{L^4}$, $P^r g_{ir} = P_i$,

$\delta_i^r a_{rhk} = a_{ihk}$.

From (21), the v-curvature tensor S_{hijk} of $C\Gamma$ is written

as, $4p_{-(m-2)}^2 S_{hijk} = 4p_{-(m-2)}^2 \Theta_{(jk)} (C_{hk}^r C_{rij})$

where, $\Theta_{(jk)}$ anti-symmetric with respect to indices j

and k. Thus,

$$4p_{-(m-2)}^2 S_{hijk} = \Theta_{(jk)} [4p_{-(m-2)}^4 a_{hk}^r a_{rij} + 2p_{-(m-2)}^2 (a_{rij} P_r H_{hk} + a_{hk}^r P_r H_{ij}) - (l_h P_k + l_k P_h) A_{ij} - (l_i P_j + l_j P_i) A_{hk} + H_{ij}^r P_r P_k + H_{hk}^r P_r P_j] \dots\dots\dots(22)$$

where,

$$A_{ij} = 2p_{-(m-2)}^2 a_{ij} - \frac{\bar{P}}{L^2} h_{ij}$$

$$H_{ij}^r = 2p_{-(m-2)}^2 \frac{2r_{-(m-1)}}{3p_{-(m-1)}^3} a_{rij} P_r + \left(1 + \frac{P^2}{L^4}\right) h_{ij}^r.$$

Proposition 5: The v-curvature tensor of a Finsler space with (λ, β) -metric is given by (22).

Next, h- and v-covariant derivatives $X_{ij}, X_i |_{j}$ of a covariant vector field X_i with respect to the Cartan connection $C\Gamma$ are defined by,

$$X_{ij} = \partial_j X_i - (\partial_r X_i) N_j^r - X_r F_{ij}^r \text{ and } X_i |_{j} = \partial_j X_i - X_r C_{ij}^r$$

where, $(F_{jk}^i, N_j^i (= F_{0j}^i), C_{jk}^i)$ are connection coefficients of $C\Gamma$ and suffix '0' means the contraction by supporting element y^i (Antonelli *et al.* 1993).

If $b_{ijh} = 0$, then for $L(\lambda, \beta)$ -metric, we have,

$$a_{ijj} = 0, a_{ijk} = 0 \dots\dots\dots(23)$$

because, $l_{ij} = 0$ and $h_{ijk} = 0$.

Then, the h-covariant differentiation of (13b), we have,

$$C_{ijk|h} = p_{-(m-2)} a_{ijk|h} \dots\dots\dots(24)$$

Therefore, the v(hv)-torsion tensor P_{ijk} is written as,

$$P_{ijk} = C_{ijk|h} y^h = C_{jk|0} = p_{-(m-2)} a_{ijk|0} \dots\dots\dots(25)$$

Definition: 7 A Finsler space is called a Berwald space, if $C_{ijk|h}$ vanishes identically and called a Landsberg space if $C_{ijk|0}$ vanishes identically.

Theorem 2: If b_i is h-covariantly constant (resp. b_{ij0}), then a Finsler space with (λ, β) -metric is a Berwald space (resp. Landsberg space) iff the tensor $a_{ijk|h}$ (resp. $a_{ijk|0}$) vanishes identically.

Now, the hv-curvature tensor P_{hijk} (Antonelli *et al.* 1993) is given by,

$$P_{hijk} = \Theta_{(hi)} (C_{ijk|h} + C_{hj}^r C_{rik|0}).$$

Now,

$$C_{hj}^r C_{rik|0} = p_{-(m-2)}^2 a_{hj}^r a_{rik|0} + \frac{1}{2} a_{hik|0} P_j - \frac{1}{2L} a_{ik|0} (l_h P_j + l_j P_h) + \frac{1}{2} a_{jik|0} P_h + \frac{r_{-(m-1)}}{2p_{-(m-1)}^3} a_{rik|0} P^r P_j P_h + \frac{1}{2} h_{jh} P^r a_{rik|0}.$$

Thus,

$$P_{hijk} = \Theta_{(h)} [a_{ijk|h} + \frac{1}{2} a_{ijk|0} P_h - \frac{1}{2L} a_{ik|0} (l_h P_j + l_j P_h) + a_{rik|0} P^r H_{jh} + a_{rik|0} A_{hj}^r] \dots\dots\dots(26)$$

where, $A_{hj}^r = p_{-(m-2)}^2 a_{hj}^r + \frac{1}{b} \frac{r_{-(m-1)}}{p_{-(m-1)}^3} P^r P_j P_h.$

Proposition 6: The (v) hv-torsion tensor P_{ijk} and hv-curvature tensor P_{hijk} for (λ, β) -metric is given by (25) and (26) respectively.

Now, the T-tensor is given by

$$T_{hijk} = LC_{hij|k} + l_i C_{hjk} + l_j C_{hik} + l_k C_{hij} + l_h C_{ijk}.$$

Now, the v-derivative of C_{hij} is given by

$$2p_{-(m-2)} C_{hij|k} = 2p_{-(m-2)}^2 a_{hij|k} + 2p_{-(m-2)}^2 |k a_{hij} - \frac{1}{L} [h_{jk} (l_i P_h + l_h P_i) + h_{ik} (l_j P_h + l_h P_j) + h_{hk} (l_i P_j + l_j P_i)] + \frac{\Pi(H_{hi} P_j |k)}{\Pi(hij)} + \frac{2r_{-(m-1)}}{3p_{-(m-1)}^3} \frac{\Pi(P_h P_i P_j |k)}{\Pi(hij)} \dots\dots\dots(27)$$

Using (6), (13b) and (27), the T-tensor for (λ, β) -metric is given by

$$T_{hijk} = \frac{1}{2p_{-(m-2)}} [2p_{-(m-2)}^2 La_{hij|k} + 2p_{-(m-2)}^2 |k La_{hij} - 2p_{-(m-2)} |k LC_{hij}] - \frac{1}{2p_{-(m-2)}} [h_{jk} (l_i P_h + l_h P_i) + h_{ik} (l_j P_h + l_h P_j) + h_{hk} (l_i P_j + l_j P_i)] + L \frac{\Pi(H_{hi} P_j |k)}{\Pi(hij)} + \frac{2r_{-(m-1)}}{3p_{-(m-1)}^3} L \frac{\Pi(P_h P_i P_j |k)}{\Pi(hij)} + p_{-(m-2)}^2 \frac{\Pi(l_h a_{ijk})}{\Pi(hijk)} + \frac{\Pi\{H_{hi} (l_j P_k + l_k P_j)\}}{\Pi(hijk)} \dots\dots\dots(28)$$

Thus,

Proposition 7: The T-tensor T_{hijk} for (λ, β) -metric is given by (28).

CONCLUSION

Present paper examined some conditions that characterize The normalized supporting element l_i , angular metric tensor h_{ij} , metric tensor g_{ij} and (h) hv-torsion tensor C_{ijk} , The reciprocal of the metric tensor g^{ij} , T-tensor T_{hijk} , C-reducile of Finsler space with (λ, β) -metric,.

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