

Inverse of an Arbitrary Vandermonde Matrix

J. López-Bonilla¹, S. Vidal-Beltrán¹, J.M. Rivera-Rebolledo²

¹ESIME-Zacatenco, Instituto Politécnico Nacional (IPN),

Anexo Edif. 3, Col. Lindavista CP 07738, México DF, E-mail: jlopezb@ipn.mx

²Depto. Física, ESFM-IPN, Edif. 9, Col. Lindavista CP 07738, México DF

Abstract. It is shown a general formula to invert any type Vandermonde matrix.

The Vandermonde [1-3] matrices have the structure:

$$\begin{pmatrix} 1 & x_1 \\ 1 & x_2 \end{pmatrix}, \begin{pmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{pmatrix}, \begin{pmatrix} 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \\ 1 & x_4 & x_4^2 & x_4^3 \end{pmatrix}, \dots \quad (1)$$

and are useful in the Lagrange interpolation [4]. Here it is exhibited a general expression to construct the inverse of a matrix of the type (1); in fact, let

$$V = \begin{pmatrix} 1 & x_1 & x_1^2 & \dots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \dots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^{n-1} \end{pmatrix}, \quad n = 2, 3, \dots \quad (2)$$

from which it is well known [2] that its determinant is not zero if the x_j are different among them, then under this last assumption there exists $V^{-1} = (A_{rk})$, and for their elements it is presented the following formula

$$A_{rk} = \frac{(-1)^{n+r}}{B_k} C_{rk}, \quad (3)$$

where:

$$B_k = \prod_{\substack{j=1 \\ j \neq k}}^n (x_k - x_j), \quad C_{nk} = 1, \quad k = 1, 2, \dots, n$$

$$C_{rk} = \sum_{i_1, \dots, i_c} x_{i_1} x_{i_2} \dots x_{i_c}, \quad c = n - r, \quad r = 1, \dots, n - 1, \quad (4)$$

$$i_j \neq k, \quad j = 1, \dots, c,$$

$$i_1 = n, n - 1, \dots, c, \quad i_2 = i_1 - 1, \dots, 1, \dots, \quad i_c = i_{c-1} - 1, \dots, 1,$$

which for $n = 2, 3, 4, \dots$ leads to the inverse matrices:

$$\frac{1}{B_2} \begin{pmatrix} x_2 & -x_1 \\ -1 & 1 \end{pmatrix}, \quad B_2 = -B_1 = x_2 - x_1,$$

$$\begin{pmatrix} \frac{x_2 x_3}{B_1} & \frac{x_1 x_3}{B_2} & \frac{x_1 x_2}{B_3} \\ -\frac{x_2 + x_3}{B_1} & -\frac{x_1 + x_3}{B_2} & -\frac{x_1 + x_2}{B_3} \\ \frac{1}{B_1} & \frac{1}{B_2} & \frac{1}{B_3} \end{pmatrix}, \quad \begin{aligned} B_1 &= (x_1 - x_2)(x_1 - x_3), \\ B_2 &= (x_2 - x_1)(x_2 - x_3), \\ B_3 &= (x_3 - x_2)(x_3 - x_1), \end{aligned} \quad (5)$$

$$\begin{pmatrix} \frac{x_2 x_3 x_4}{B_1} & \frac{x_1 x_3 x_4}{B_2} & \frac{x_1 x_2 x_4}{B_3} & \frac{x_1 x_2 x_3}{B_4} \\ \frac{x_2 x_3 + x_2 x_4 + x_3 x_4}{B_1} & \frac{x_1 x_3 + x_1 x_4 + x_3 x_4}{B_2} & \frac{x_1 x_2 + x_1 x_4 + x_2 x_4}{B_3} & \frac{x_1 x_2 + x_1 x_3 + x_2 x_3}{B_4} \\ \frac{x_2 + x_3 + x_4}{B_1} & \frac{x_1 + x_3 + x_4}{B_2} & \frac{x_1 + x_2 + x_4}{B_3} & \frac{x_1 + x_2 + x_3}{B_4} \\ \frac{1}{B_1} & \frac{1}{B_2} & \frac{1}{B_3} & \frac{1}{B_4} \end{pmatrix}$$

with:

$$B_1 = (x_1 - x_2)(x_1 - x_3)(x_1 - x_4), \quad B_2 = (x_2 - x_1)(x_2 - x_3)(x_2 - x_4),$$

$$B_3 = (x_3 - x_1)(x_3 - x_2)(x_3 - x_4), \quad B_4 = (x_4 - x_1)(x_4 - x_2)(x_4 - x_3),$$

which in turn give the identity matrix after multiplication by (1).

Turner [5], see its relations (6) and (8), showed that $V_{n \times n}^{-1}$ is the product of two triangular matrices, which can be illustrated with the inverse matrices (5):

$$V_{2 \times 2}^{-1} = \begin{pmatrix} 1 & -x_1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \frac{1}{B_1} & \frac{1}{B_2} \end{pmatrix},$$

$$V_{3 \times 3}^{-1} = \begin{pmatrix} 1 & -x_1 & x_1 x_2 \\ 0 & 1 & -(x_1 + x_2) \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{x_1 - x_2} & \frac{1}{x_2 - x_1} & 0 \\ \frac{1}{B_1} & \frac{1}{B_2} & \frac{1}{B_3} \end{pmatrix}, \quad (6)$$

$$V_{4 \times 4}^{-1} = \begin{pmatrix} 1 & -x_1 & x_1 x_2 & -x_1 x_2 x_3 \\ 0 & 1 & -(x_1 + x_2) & x_1 x_2 + x_2 x_3 + x_1 x_3 \\ 0 & 0 & 1 & -(x_1 + x_2 + x_3) \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \underline{T},$$

with:

$$\underline{T} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ \frac{1}{x_1 - x_2} & \frac{1}{x_2 - x_1} & 0 & 0 \\ \frac{1}{(x_1 - x_2)(x_1 - x_3)} & \frac{1}{(x_2 - x_1)(x_2 - x_3)} & \frac{1}{(x_3 - x_1)(x_3 - x_2)} & 0 \\ \frac{1}{B_1} & \frac{1}{B_2} & \frac{1}{B_3} & \frac{1}{B_4} \end{pmatrix}.$$

The expressions (3) and (4) are easy to manage with MAPLE or by means of any Symbolic Program, with an immediate application to polynomials interpolation problems [4].

REFERENCES

- [1] C. Lanczos, Applied analysis, Dover, New York (1988)
- [2] F.D. Parker, Am. Math. Monthly 71, No. 4 (1964) 410 - 411
- [3] J.H. Wilkinson, The algebraic eigenvalue problem, Clarendon Press, Oxford (1965)
- [4] L.R. Turner, Lewis Research Center-NASA, Cleveland, Ohio (1966)
- [5] R.A. Horn and Ch.R. Johnson, Matrix analysis, Cambridge University Press (1990)